

# Review of Chapter 6

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In fact, this case is the only way a matrix can be diagonalizable:

## Theorem

*An  $n \times n$  matrix  $A$  is diagonalizable if and only if  $\mathbb{R}^n$  has a basis consisting of eigenvectors of  $A$ . It happens when the sum of the dimensions of the eigenspaces is  $n$ . In that case the diagonal elements are the eigenvalues of  $A$ .*



Example: Diagonalize the following matrix, or else prove it is not diagonalizable:

$$A = \begin{pmatrix} 1 & 1 & -1 \\ 0 & 2 & 0 \\ -1 & 1 & 1 \end{pmatrix}$$

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First step: find the eigenvalues.

$$\begin{vmatrix} 1 - \lambda & 1 & 1 \\ 0 & 2 - \lambda & 0 \\ 1 & 1 & 1 - \lambda \end{vmatrix} = (2 - \lambda)((1 - \lambda)^2 - 1) = (2 - \lambda)(\lambda^2 - 2\lambda)$$

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Equating this to 0 we get two roots:  $\lambda = 0$  and a double root  $\lambda = 2$ .

Second step: Find the eigenspaces.

$$A - 2I = \begin{pmatrix} -1 & 1 & 1 \\ 0 & 0 & 0 \\ 1 & 1 & -1 \end{pmatrix} \xrightarrow{5 \text{ EROs}} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

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The equations this gives are  $x_1 = x_3$  and  $x_2 = 0$ . The eigenspace is therefore

$$\left\{ \left\{ \begin{pmatrix} \alpha \\ 0 \\ \alpha \end{pmatrix} \mid \alpha \in \mathbb{R} \right\} \text{ with basis } \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\}$$

The eigenspace for  $\lambda = 0$

$$A - 0I = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 2 & 0 \\ 1 & 1 & 1 \end{pmatrix} \xrightarrow{3 \text{ EROs}} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

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There is one special case where a matrix is assured to be diagonalizable: when there are as many different eigenvalues as the dimension.

This is because each eigenspace has dimension at least one, and in this case there will be  $n$  eigenspaces.

## Some Examples

(1) Find the eigenvalues of the matrix  $A = \begin{pmatrix} 3 & 0 & 0 \\ 1 & 3 & 1 \\ 2 & -1 & 1 \end{pmatrix}$

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Find  $\det(A - \lambda I)$

$$\begin{vmatrix} 3 - \lambda & 0 & 0 \\ 1 & 3 - \lambda & 1 \\ 2 & -1 & 1 - \lambda \end{vmatrix} = (3 - \lambda)(\lambda^2 - 4\lambda + 4)$$

Equate this to 0 and solve to get  $\lambda = 3, 2, 2$ .

(2) For each eigenvalue of  $A$ , find a basis for its eigenspace.

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For  $\lambda = 3$ , the matrix

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So solutions of  $(A - 3I)\mathbf{x} = 0$  are  $\mathbf{x} = \begin{pmatrix} -\alpha \\ -4\alpha \\ \alpha \end{pmatrix}$ ,

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For  $\lambda = 2$  the matrix

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(3) We can conclude that  $A$  is not diagonalizable.

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The determinant of  $B - \lambda I$  is

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$$S^{-1}BS = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$



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### Theorem

*Let  $A$  be a symmetric  $n \times n$  matrix, (i.e.,  $A^T = A$ ) and suppose  $\lambda_1$  and  $\lambda_2$  are two different eigenvalues. If  $\mathbf{x}_1$  and  $\mathbf{x}_2$  are the respective eigenvectors then  $\mathbf{x}_1 \perp \mathbf{x}_2$ .*

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### Theorem

*If  $A$  is a symmetric matrix then all eigenvalues are real, and there an orthonormal basis for  $\mathbb{R}^n$  consisting of eigenvectors of  $A$ .*



Example: Find an orthonormal basis of eigenvectors for  $A = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 1 & 2 \end{pmatrix}$

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Eigenvalues:  $\begin{vmatrix} 2 - \lambda & 0 & 0 \\ 0 & 2 - \lambda & 1 \\ 0 & 1 & 2 - \lambda \end{vmatrix} = (2 - \lambda)((2 - \lambda)^2 - 1) = (2 - \lambda)(\lambda^2 - 4\lambda + 3).$

Equate to zero to get  $\lambda = 1, 2, 3.$



For  $\lambda = 1$ , the matrix

$$A - I = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{pmatrix} \xrightarrow{R_3 - R_2} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

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A basis for the eigenspace is  $\begin{pmatrix} 0 & -1 & 1 \end{pmatrix}^T$ . Normalize to get  $\mathbf{q}_1 = \begin{pmatrix} 0 & -1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix}^T$ .

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For  $\lambda = 2$  the matrix

$$A - 2I = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \xrightarrow{R_3 \leftrightarrow R_1} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

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A basis for the eigenspace is  $\mathbf{q}_2 = \begin{pmatrix} 1 & 0 & 0 \end{pmatrix}^T$ . The norm is already 1. Note that  $\mathbf{q}_1 \perp \mathbf{q}_2$ .

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For  $\lambda = 4$  we get a one-dimensional eigenspace with basis  $\begin{pmatrix} 1 & 1 & 1 \end{pmatrix}^T$ .

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For  $\lambda = 4$  we get a one-dimensional eigenspace with basis  $\begin{pmatrix} 1 & 1 & 1 \end{pmatrix}^T$ .

For  $\lambda = 1$ , the matrix  $A - I$  is

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \xrightarrow[\begin{matrix} R_2 - R_1 \\ R_3 - R_1 \end{matrix}]{\quad} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

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$$\begin{pmatrix} -1 & 1 & 0 \end{pmatrix}^T \text{ and } \begin{pmatrix} -1 & 0 & 1 \end{pmatrix}^T$$

These are not orthogonal, though they are a basis for the eigenspace. If we want an orthonormal basis we can apply the Gram-Schmidt process to these two to get

$$\begin{pmatrix} -1/\sqrt{2} & 1/\sqrt{2} & 0 \end{pmatrix} \text{ and } \begin{pmatrix} -1/\sqrt{6} & -1/\sqrt{6} & 2/\sqrt{6} \end{pmatrix}^T$$



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These two are orthogonal to the eigenvector for  $\lambda = 4$ . If we normalize that we get  $\begin{pmatrix} 1/\sqrt{3} & 1/\sqrt{3} & 1/\sqrt{3} \end{pmatrix}$  and the three together give us an orthonormal basis for  $\mathbb{R}^3$  of eigenvectors for  $A$ .