# The Gram-Schmidt Process 

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## Theorem (Gram-Schmidt)

If $\left\{\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{r}\right\}$ is an independent set in an inner product space $V$ then there exists and orthonormal set $\left\{\mathbf{u}_{1}, \mathbf{u}_{2}, \ldots, \mathbf{u}_{r}\right\}$ such that $\operatorname{Span}\left(\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{r}\right)=\operatorname{Span}\left(\mathbf{u}_{1}, \mathbf{u}_{2}, \ldots, \mathbf{u}_{r}\right)$.

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The process takes $r$ steps, and at the end of step $j$ the vectors $\mathbf{u}_{1}, \ldots, \mathbf{u}_{j}$ have the same span as $\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{j}$.

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The process takes $r$ steps, and at the end of step $j$ the vectors $\mathbf{u}_{1}, \ldots, \mathbf{u}_{j}$ have the same span as $\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{j}$. So, by the last step the set is found. If $\left\{\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{r}\right\}$ is a basis for a subspace $S$ of $V$, then $\left\{\mathbf{u}_{1}, \mathbf{u}_{2}, \ldots, \mathbf{u}_{r}\right\}$ is an orthonormal basis for $S$.

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## Theorem (Gram-Schmidt)

If $\left\{\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{r}\right\}$ is an independent set in an inner product space $V$ then there exists and orthonormal set $\left\{\mathbf{u}_{1}, \mathbf{u}_{2}, \ldots, \mathbf{u}_{r}\right\}$ such that $\operatorname{Span}\left(\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{r}\right)=\operatorname{Span}\left(\mathbf{u}_{1}, \mathbf{u}_{2}, \ldots, \mathbf{u}_{r}\right)$.

The process takes $r$ steps, and at the end of step $j$ the vectors $\mathbf{u}_{1}, \ldots, \mathbf{u}_{j}$ have the same span as $\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{j}$. So, by the last step the set is found. If $\left\{\mathbf{x}_{1}, \mathbf{x}_{2}, \ldots, \mathbf{x}_{r}\right\}$ is a basis for a subspace $S$ of $V$, then $\left\{\mathbf{u}_{1}, \mathbf{u}_{2}, \ldots, \mathbf{u}_{r}\right\}$ is an orthonormal basis for $S$. When computing by hand, it is quite a bit easier to first create an orthogonal set $\mathbf{v}_{1}, \ldots, \mathbf{v}_{r}$ and then normalize them at the end by $\mathbf{u}_{j}=\left(1 /\left\|\mathbf{v}_{j}\right\|\right) \mathbf{v}_{j}$.

The steps

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- Step 3: set $\mathbf{v}_{3}=\mathbf{x}_{3}-\mathbf{p}_{2}$ where $\mathbf{p}_{2}$ is the projection of $\mathbf{x}_{3}$ onto $\operatorname{Span}\left(\mathbf{v}_{1}, \mathbf{v}_{2}\right)$.

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$$

- Steps $k=4$ thru $r$ : set $\mathbf{v}_{k}=\mathbf{x}_{k}-\mathbf{p}_{k-1}$ where $\mathbf{p}_{k-1}$ is the projection of $\mathbf{x}_{k}$ onto $\operatorname{Span}\left(\mathbf{v}_{1}, \ldots, \mathbf{v}_{k-1}\right)$.

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$$
\mathbf{v}_{k}=\mathbf{x}_{k}-\sum_{i=1}^{k-1} \frac{\left\langle\mathbf{x}_{k}, \mathbf{v}_{i}\right\rangle}{\left\langle\mathbf{v}_{i}, \mathbf{v}_{i}\right\rangle} \mathbf{v}_{i}
$$

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- Steps $k=4$ thru $r$ : set $\mathbf{v}_{k}=\mathbf{x}_{k}-\mathbf{p}_{k-1}$ where $\mathbf{p}_{k-1}$ is the projection of $\mathbf{x}_{k}$ onto $\operatorname{Span}\left(\mathbf{v}_{1}, \ldots, \mathbf{v}_{k-1}\right)$. That is

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\mathbf{v}_{k}=\mathbf{x}_{k}-\sum_{i=1}^{k-1} \frac{\left\langle\mathbf{x}_{k}, \mathbf{v}_{i}\right\rangle}{\left\langle\mathbf{v}_{i}, \mathbf{v}_{i}\right\rangle} \mathbf{v}_{i}
$$

Then step $r+1$ : set $\mathbf{u}_{j}=\left(1 /\left\|\mathbf{v}_{j}\right\|\right) \mathbf{v}_{j}$ for each $j$.

## Example: find an orthonormal basis for the span of

$$
\mathbf{x}_{1}=\left(\begin{array}{l}
1 \\
1 \\
0 \\
1
\end{array}\right), \mathbf{x}_{2}=\left(\begin{array}{l}
1 \\
0 \\
1 \\
1
\end{array}\right), \mathbf{x}_{3}=\left(\begin{array}{l}
0 \\
1 \\
1 \\
1
\end{array}\right)
$$

Example: find an orthonormal basis for the span of

$$
\begin{aligned}
& \mathbf{x}_{1}=\left(\begin{array}{l}
1 \\
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1
\end{array}\right), \mathbf{x}_{2}=\left(\begin{array}{l}
1 \\
0 \\
1 \\
1
\end{array}\right), \mathbf{x}_{3}=\left(\begin{array}{l}
0 \\
1 \\
1 \\
1
\end{array}\right) \\
& \mathbf{v}_{1}=\mathbf{x}_{1}=\left(\begin{array}{l}
1 \\
1 \\
0 \\
1
\end{array}\right) .
\end{aligned}
$$

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1 \\
1
\end{array}\right), \mathbf{x}_{3}=\left(\begin{array}{l}
0 \\
1 \\
1 \\
1
\end{array}\right) . \\
& \mathbf{v}_{1}=\mathbf{x}_{1}=\left(\begin{array}{l}
1 \\
1 \\
0 \\
1
\end{array}\right) . \quad \mathbf{v}_{2}=\mathbf{x}_{2}-\mathbf{p}_{1}=\left(\begin{array}{l}
1 \\
0 \\
1 \\
1
\end{array}\right)-\frac{2}{3}\left(\begin{array}{l}
1 \\
1 \\
0 \\
1
\end{array}\right)=\left(\begin{array}{c}
1 / 3 \\
-2 / 3 \\
1 \\
1 / 3
\end{array}\right) .
\end{aligned}
$$

Example: find an orthonormal basis for the span of
$\mathbf{x}_{1}=\left(\begin{array}{l}1 \\ 1 \\ 0 \\ 1\end{array}\right), \mathbf{x}_{2}=\left(\begin{array}{l}1 \\ 0 \\ 1 \\ 1\end{array}\right), \mathbf{x}_{3}=\left(\begin{array}{l}0 \\ 1 \\ 1 \\ 1\end{array}\right)$.
$\mathbf{v}_{1}=\mathbf{x}_{1}=\left(\begin{array}{l}1 \\ 1 \\ 0 \\ 1\end{array}\right) . \quad \mathbf{v}_{2}=\mathbf{x}_{2}-\mathbf{p}_{1}=\left(\begin{array}{l}1 \\ 0 \\ 1 \\ 1\end{array}\right)-\frac{2}{3}\left(\begin{array}{l}1 \\ 1 \\ 0 \\ 1\end{array}\right)=\left(\begin{array}{c}1 / 3 \\ -2 / 3 \\ 1 \\ 1 / 3\end{array}\right)$
$\mathbf{v}_{3}=\mathbf{x}_{3}-\mathbf{p}_{2}=\left(\begin{array}{l}0 \\ 1 \\ 1 \\ 1\end{array}\right)-\frac{2}{3}\left(\begin{array}{l}1 \\ 1 \\ 0 \\ 1\end{array}\right)-\frac{2 / 3}{5 / 3}\left(\begin{array}{r}1 / 3 \\ -2 / 3 \\ 1 \\ 1 / 3\end{array}\right)=\left(\begin{array}{r}-4 / 5 \\ 3 / 5 \\ 3 / 5 \\ 1 / 5\end{array}\right)$.

Since $\left\|\mathbf{v}_{1}\right\|=\sqrt{3},\left\|\mathbf{v}_{2}\right\|=\sqrt{15} / 3$ and $\left\|\mathbf{v}_{3}\right\|=(\sqrt{35}) / 5$ we get the orthonormal basis

$$
\mathbf{u}_{1}=\left(\begin{array}{c}
1 / \sqrt{3} \\
1 / \sqrt{3} \\
0 \\
1 / \sqrt{3}
\end{array}\right), \quad \mathbf{u}_{2}=\left(\begin{array}{r}
1 / \sqrt{15} \\
-2 / \sqrt{15} \\
3 / \sqrt{15} \\
1 / \sqrt{15}
\end{array}\right), \quad \mathbf{u}_{3}=\left(\begin{array}{r}
-4 / \sqrt{35} \\
3 / \sqrt{35} \\
3 / \sqrt{35} \\
1 / \sqrt{35}
\end{array}\right) .
$$

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1 / \sqrt{15} \\
-2 / \sqrt{15} \\
3 / \sqrt{15} \\
1 / \sqrt{15}
\end{array}\right), \quad \mathbf{u}_{3}=\left(\begin{array}{r}
-4 / \sqrt{35} \\
3 / \sqrt{35} \\
3 / \sqrt{35} \\
1 / \sqrt{35}
\end{array}\right)
$$

A further simplification: since the vs don't have to have norm equal to 1 , we can replace $\mathbf{v}_{2}$ by any multiple of it. So taking $\mathbf{v}_{2}=\left(\begin{array}{r}1 \\ -2 \\ 3 \\ 1\end{array}\right)$ instead of what we used, the next step simplifies to:

$$
\mathbf{v}_{3}=\mathbf{x}_{3}-\mathbf{p}_{2}=\left(\begin{array}{l}
0 \\
1 \\
1 \\
1
\end{array}\right)-\frac{2}{3}\left(\begin{array}{l}
1 \\
1 \\
0 \\
1
\end{array}\right)-\frac{2}{15}\left(\begin{array}{r}
1 \\
-2 \\
3 \\
1
\end{array}\right)=\left(\begin{array}{r}
-4 / 5 \\
3 / 5 \\
3 / 5 \\
1 / 5
\end{array}\right)
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\end{array}\right)
$$

and then we could also use $\mathbf{v}_{3}=\left(\begin{array}{r}-4 \\ 3 \\ 3 \\ 1\end{array}\right)$.

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0 \\
1 \\
1 \\
1
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1 \\
1 \\
0 \\
1
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and then we could also use $\mathbf{v}_{3}=\left(\begin{array}{r}-4 \\ 3 \\ 3 \\ 1\end{array}\right)$.
Because the norms are, respectively, $\sqrt{3}, \sqrt{15}$, and $\sqrt{35}$, we will end up with the same orthonormal basis.
The Gram-Schmidt process can be applied to a dependent set, but it will sometimes produce $\mathbf{v}_{j}=\mathbf{0}$. In that case we discard $\mathbf{x}_{j}$ and continue with the rest.

Sometimes one of the $\mathbf{x}_{j}$ is orthogonal to all the previous $\mathbf{x}_{i}$. In that case we get $\mathbf{p}_{j-1}=\mathbf{0}$ and $\mathbf{v}_{j}=\mathbf{x}_{j}$.
Example: Find an orthonormal basis for $\mathbb{R}^{3}$ Using the Gram-Schmidt on the set $\mathbf{x}_{1}=\left(\begin{array}{l}1 \\ 0 \\ 0\end{array}\right), \quad \mathbf{x}_{2}=\left(\begin{array}{l}0 \\ 1 \\ 1\end{array}\right), \quad \mathbf{x}_{3}=\left(\begin{array}{l}1 \\ 0 \\ 1\end{array}\right)$

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Example: Find an orthonormal basis for $\mathbb{R}^{3}$ Using the Gram-Schmidt on the set

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\begin{aligned}
& \mathbf{x}_{1}=\left(\begin{array}{l}
1 \\
0 \\
0
\end{array}\right), \mathbf{x}_{2}=\left(\begin{array}{l}
0 \\
1 \\
1
\end{array}\right), \mathbf{x}_{3}=\left(\begin{array}{l}
1 \\
0 \\
1
\end{array}\right) \\
& \mathbf{v}_{1}=\mathbf{x}_{1}=\left(\begin{array}{l}
1 \\
0 \\
0
\end{array}\right) .
\end{aligned}
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\end{array}\right), \mathbf{x}_{3}=\left(\begin{array}{l}
1 \\
0 \\
1
\end{array}\right) \\
& \mathbf{v}_{1}=\mathbf{x}_{1}=\left(\begin{array}{l}
1 \\
0 \\
0
\end{array}\right) .
\end{aligned}
$$

$$
\mathbf{v}_{2}=\mathbf{x}_{2}-\mathbf{p}_{1}=\left(\begin{array}{l}
0 \\
1 \\
1
\end{array}\right)-\frac{0}{1}\left(\begin{array}{l}
1 \\
0 \\
0
\end{array}\right)=\left(\begin{array}{l}
0 \\
1 \\
1
\end{array}\right)
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\end{array}\right) .
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0 \\
0
\end{array}\right)=\left(\begin{array}{l}
0 \\
1 \\
1
\end{array}\right)
$$

$$
\mathbf{v}_{3}=\mathbf{x}_{3}-\mathbf{p}_{2}=\left(\begin{array}{c}
1 \\
0 \\
1
\end{array}\right)-\frac{1}{1}\left(\begin{array}{l}
1 \\
0 \\
0
\end{array}\right)-\frac{1}{2}\left(\begin{array}{l}
0 \\
1 \\
1
\end{array}\right)=\left(\begin{array}{c}
0 \\
-1 / 2 \\
1 / 2
\end{array}\right)
$$

So, $\mathbf{u}_{1}=\left(\begin{array}{l}1 \\ 0 \\ 0\end{array}\right), \quad \mathbf{u}_{2}=\left(\begin{array}{c}0 \\ 1 / \sqrt{2} \\ 1 / \sqrt{2}\end{array}\right), \quad \mathbf{u}_{3}=\left(\begin{array}{c}0 \\ -1 / \sqrt{2} \\ 1 / \sqrt{2}\end{array}\right)$.

So, $\mathbf{u}_{1}=\left(\begin{array}{l}1 \\ 0 \\ 0\end{array}\right), \mathbf{u}_{2}=\left(\begin{array}{c}0 \\ 1 / \sqrt{2} \\ 1 / \sqrt{2}\end{array}\right), \quad \mathbf{u}_{3}=\left(\begin{array}{c}0 \\ -1 / \sqrt{2} \\ 1 / \sqrt{2}\end{array}\right)$.
The transition matrix from the basis $\mathcal{B}=\left[\mathbf{x}_{1}, \mathbf{x}_{2}, \mathbf{x}_{3}\right]$ to the basis $\mathcal{C}=\left[\mathbf{u}_{1}, \mathbf{u}_{2}, \mathbf{u}_{3}\right]$ has a particularly nice form.

So, $\mathbf{u}_{1}=\left(\begin{array}{l}1 \\ 0 \\ 0\end{array}\right), \mathbf{u}_{2}=\left(\begin{array}{c}0 \\ 1 / \sqrt{2} \\ 1 / \sqrt{2}\end{array}\right), \quad \mathbf{u}_{3}=\left(\begin{array}{c}0 \\ -1 / \sqrt{2} \\ 1 / \sqrt{2}\end{array}\right)$.
The transition matrix from the basis $\mathcal{B}=\left[\mathbf{x}_{1}, \mathbf{x}_{2}, \mathbf{x}_{3}\right]$ to the basis $\mathcal{C}=\left[\mathbf{u}_{1}, \mathbf{u}_{2}, \mathbf{u}_{3}\right]$ has a particularly nice form.
The transition matrix from $\mathcal{B}$ to the standard basis $\mathcal{E}$ is $A=\left(\begin{array}{lll}\mathbf{x}_{1} & \mathbf{x}_{2} & \mathbf{x}_{3}\end{array}\right)$.

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Something like this happens in every Gram-Scmidt process. Start with an $n \times k$ matrix $A$, whose columns are independent vectors $\mathbf{x}_{1}, \ldots, \mathbf{x}_{k}$ in $\mathbb{R}^{n}$.

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Something like this happens in every Gram-Scmidt process. Start with an $n \times k$ matrix $A$, whose columns are independent vectors $\mathbf{x}_{1}, \ldots, \mathbf{x}_{k}$ in $\mathbb{R}^{n}$. Apply Gram-Schmidt to them to get orthonormal vectors $\mathbf{q}_{1}, \ldots, \mathbf{q}_{k}$.

If we let $Q=\left(\begin{array}{lll}\mathbf{q}_{1} & \cdots & \mathbf{q}_{k}\end{array}\right)$ then $R=Q^{T} A$ is an upper triangular $k \times k$ matrix and $A=Q R$ where $Q$ is an $n \times k$ with orthonormal columns. This is called the QR-factorization of $A$.

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Note that $R$ is a square matrix. Also its diagonals are $\mathbf{q}_{j}^{T} \mathbf{x}_{j}$. These are not zero because $\mathbf{q}_{j}=\left(1 /\left\|\mathbf{v}_{j}\right\|\right) \mathbf{v}_{j}$ where $\mathbf{v}_{j}$ has the form

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$$
\mathbf{v}_{j}=\mathbf{x}_{j}-\left(\text { a linear combination of } \mathbf{v}_{i}, i<j\right)
$$

which means

$$
\mathbf{x}_{j}=\mathbf{v}_{j}+\left(\text { a linear combination of } \mathbf{v}_{i}, i<j\right)
$$

and that says that $\mathbf{q}_{j}^{T} \mathbf{x}_{j}=\left(1 /\left\|\mathbf{v}_{j}\right\|\right) \mathbf{v}_{j}^{T} \mathbf{v}_{j}=\left\|\mathbf{v}_{j}\right\| \neq 0$.

Examples: our first Gram-Schmidt example gives us

$$
A=\left(\begin{array}{lll}
1 & 1 & 0 \\
1 & 0 & 1 \\
0 & 1 & 1 \\
1 & 1 & 1
\end{array}\right), \quad Q=\left(\begin{array}{ccc}
1 / \sqrt{3} & 1 / \sqrt{15} & -4 / \sqrt{35} \\
1 / \sqrt{3} & -2 / \sqrt{15} & 3 / \sqrt{35} \\
0 & 3 / \sqrt{15} & 3 / \sqrt{35} \\
1 / \sqrt{3} & 1 / \sqrt{15} & 1 / \sqrt{35}
\end{array}\right)
$$

and

$$
Q^{T} A=R=\left(\begin{array}{ccc}
3 / \sqrt{3} & 2 / \sqrt{3} & 2 / \sqrt{3} \\
0 & 5 / \sqrt{15} & 2 / \sqrt{15} \\
0 & 0 & 7 / \sqrt{35}
\end{array}\right)
$$

Our second Gram-Schmidt example gives us:

$$
A=\left(\begin{array}{lll}
1 & 0 & 1 \\
0 & 1 & 0 \\
0 & 1 & 1
\end{array}\right), \quad Q=\left(\begin{array}{rrr}
1 & 0 & 0 \\
0 & 1 / \sqrt{2} & -1 / \sqrt{2} \\
0 & 1 / \sqrt{2} & 1 / \sqrt{2}
\end{array}\right)
$$

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$$
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1 & 0 & 1 \\
0 & 1 & 0 \\
0 & 1 & 1
\end{array}\right), \quad Q=\left(\begin{array}{rrr}
1 & 0 & 0 \\
0 & 1 / \sqrt{2} & -1 / \sqrt{2} \\
0 & 1 / \sqrt{2} & 1 / \sqrt{2}
\end{array}\right)
$$

and

$$
Q^{T} A=R=\left(\begin{array}{ccc}
1 & 0 & 1 \\
0 & 2 / \sqrt{2} & 1 / \sqrt{2} \\
0 & 0 & 1 / \sqrt{2}
\end{array}\right)
$$

The $Q R$ factorization of $A$ allows a simplified calculation of least squares problems.

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It is also particularly easy to solve because $Q^{T} A=R$ is upper triangular and $R \mathbf{x}=Q^{T} \mathbf{b}$ allows a relatively quick solution via back substitution.

Example (using the $A, Q$ and $R$ from earlier): solve

$$
\left(\begin{array}{lll}
1 & 0 & 1 \\
0 & 1 & 0 \\
0 & 1 & 1
\end{array}\right) \mathbf{x}=\left(\begin{array}{l}
1 \\
2 \\
3
\end{array}\right)
$$

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1 \\
2 \\
3
\end{array}\right)
$$

Multiplying by $Q^{T}$ gives

$$
\left(\begin{array}{ccc}
1 & 0 & 1 \\
0 & 2 / \sqrt{2} & 1 / \sqrt{2} \\
0 & 0 & 1 / \sqrt{2}
\end{array}\right) \mathbf{x}=\left(\begin{array}{r}
1 \\
5 / \sqrt{2} \\
1 / \sqrt{2}
\end{array}\right)
$$

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2 \\
3
\end{array}\right)
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1 & 0 & 1 \\
0 & 2 / \sqrt{2} & 1 / \sqrt{2} \\
0 & 0 & 1 / \sqrt{2}
\end{array}\right) \mathbf{x}=\left(\begin{array}{r}
1 \\
5 / \sqrt{2} \\
1 / \sqrt{2}
\end{array}\right)
$$

This is a little easier to handle if we multiply the second and third rows (equations) by $\sqrt{2}$ :

$$
\left(\begin{array}{lll}
1 & 0 & 1 \\
0 & 2 & 1 \\
0 & 0 & 1
\end{array}\right) \mathbf{x}=\left(\begin{array}{l}
1 \\
5 \\
1
\end{array}\right)
$$

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$$
\left(\begin{array}{lll}
1 & 0 & 1 \\
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0 & 1 & 1
\end{array}\right) \mathbf{x}=\left(\begin{array}{l}
1 \\
2 \\
3
\end{array}\right)
$$

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$$
\left(\begin{array}{ccc}
1 & 0 & 1 \\
0 & 2 / \sqrt{2} & 1 / \sqrt{2} \\
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0 & 2 & 1 \\
0 & 0 & 1
\end{array}\right) \mathbf{x}=\left(\begin{array}{l}
1 \\
5 \\
1
\end{array}\right)
$$

This has solution $\mathbf{x}=\left(\begin{array}{lll}0 & 2 & 1\end{array}\right)^{T}$.

