

Orthogonal Bases (cont.)

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MASC

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$$\langle \mathbf{x}, \mathbf{y} \rangle = 3 \cdot (-1) + 2(2 \cdot 2) + 3(1 \cdot 2) = 11$$

$$\langle \mathbf{x}, \mathbf{x} \rangle = 3^2 + 2(2)^2 + 3(1)^2 = 20$$

$$\langle \mathbf{y}, \mathbf{y} \rangle = (-1)^2 + 2(2)^2 + 3(2)^2 = 21$$

Then the Cauchy-Schwarz Inequality predicts $11 \leq \sqrt{20}\sqrt{21} \approx 20.5$.

If we let $A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \sqrt{2} & 0 \\ 0 & 0 & \sqrt{3} \end{pmatrix}$, then this inner product is the same as

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The triangle inequality for the same inner product and the same vectors:

$$\|\mathbf{x} + \mathbf{y}\| = \sqrt{2^2 + 2(4)^2 + 3(3)^2} = \sqrt{63} \approx 7.94$$

$$\|\mathbf{x}\| = \sqrt{3^2 + 2(2)^2 + 3(1)^2} = \sqrt{20} \approx 4.47$$

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and $7.94 \leq 4.47 + 4.58$.

If we use the scalar product for our inner product, we get

$$\mathbf{x}^T \mathbf{y} = 3 \cdot (-1) + 2 \cdot 2 + 1 \cdot 2 = 3$$

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Two subspaces S and T of V are orthogonal if $\mathbf{x} \perp \mathbf{y}$ for every \mathbf{x} in S and \mathbf{y} in T .

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The orthogonal complement of S is the set of vectors \mathbf{x} in V such that $\mathbf{x} \perp \mathbf{y}$ for every vector \mathbf{y} in S .

Just as in \mathbb{R}^n with the scalar product, we have

1. If S and T are orthogonal and \mathbf{x} belongs to both, then $\langle \mathbf{x}, \mathbf{x} \rangle = 0$ and so $\mathbf{x} = \mathbf{0}$

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2. S^\perp is a subspace of V : if \mathbf{u} and \mathbf{v} belong to S^\perp and $\mathbf{x} \in S$, then $\langle \alpha\mathbf{u} + \beta\mathbf{v}, \mathbf{x} \rangle = \alpha \langle \mathbf{u}, \mathbf{x} \rangle + \beta \langle \mathbf{v}, \mathbf{x} \rangle = 0 + 0$. Thus $\alpha\mathbf{u} + \beta\mathbf{v} \in S^\perp$.

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5. If \mathbf{x} is any vector in V then there exist unique vectors $\mathbf{u} \in S$ and $\mathbf{v} \in S^\perp$ such that $\mathbf{x} = \mathbf{u} + \mathbf{v}$. The vector \mathbf{u} is the closest vector in S to \mathbf{x} . That is, $\|\mathbf{x} - \mathbf{u}\| \leq \|\mathbf{x} - \mathbf{y}\|$ for all $\mathbf{y} \in S$.

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Just as in \mathbb{R}^3 , $\mathbf{x} - \mathbf{p}$ is orthogonal to \mathbf{y} :

$$\begin{aligned}\langle \mathbf{y}, \mathbf{x} - \mathbf{p} \rangle &= \langle \mathbf{y}, \mathbf{x} \rangle - \langle \mathbf{y}, \mathbf{p} \rangle \\ &= \langle \mathbf{y}, \mathbf{x} \rangle - \left\langle \mathbf{y}, \frac{\langle \mathbf{x}, \mathbf{y} \rangle}{\langle \mathbf{y}, \mathbf{y} \rangle} \mathbf{y} \right\rangle \\ &= \langle \mathbf{y}, \mathbf{x} \rangle - \frac{\langle \mathbf{x}, \mathbf{y} \rangle}{\langle \mathbf{y}, \mathbf{y} \rangle} \langle \mathbf{y}, \mathbf{y} \rangle \\ &= \langle \mathbf{y}, \mathbf{x} \rangle - \langle \mathbf{x}, \mathbf{y} \rangle = 0\end{aligned}$$

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A set $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$ is said to be *orthogonal* if $\mathbf{v}_i \perp \mathbf{v}_j$ for each $i \neq j$. If it is orthogonal and $\|\mathbf{v}_j\| = 1$ for each j , we call it *orthonormal*.

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Just as in \mathbb{R}^n we have

1. Every finite dimensional subset of V has an orthonormal basis.
2. If S is a subspace of V with an orthogonal basis $\{\mathbf{v}_1, \dots, \mathbf{v}_r\}$ and \mathbf{x} is any vector in V . Then the closest vector in S to \mathbf{x} is

$$\mathbf{p} = \sum_{j=1}^r \frac{\langle \mathbf{x}, \mathbf{v}_j \rangle}{\langle \mathbf{v}_j, \mathbf{v}_j \rangle} \mathbf{v}_j$$

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4. Every orthogonal set of nonzero vectors is independent.

Matrices with orthogonal columns

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$$\mathbf{a}_i^T \mathbf{a}_j = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j \end{cases}$$

This means that $A^T A = I$, the $k \times k$ identity matrix.

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If it happens that $n = k$ so that A is a square matrix, then this tells us that A is invertible and $A^{-1} = A^T$.

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If it happens that $n = k$ so that A is a square matrix, then this tells us that A is invertible and $A^{-1} = A^T$. In this case only, we also have $AA^T = I$ and this tells us that A^T also has orthonormal columns.

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$$\cos \theta = \frac{\langle Q\mathbf{x}, Q\mathbf{y} \rangle}{\|Q\mathbf{x}\| \|Q\mathbf{y}\|} = \frac{\langle \mathbf{x}, \mathbf{y} \rangle}{\|\mathbf{x}\| \|\mathbf{y}\|}$$

and that is the cosine of the angle between \mathbf{x} and \mathbf{y} .

If \mathcal{B} is an orthonormal basis, and Q is the matrix whose columns are the elements of \mathcal{B} , then Q is the transition matrix from \mathcal{B} to \mathcal{E} and Q^T is the transition matrix from \mathcal{E} to \mathcal{B} .

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If $\mathcal{B} = [\mathbf{u}_1, \dots, \mathbf{u}_n]$ is an orthonormal basis in an inner product space V and \mathbf{v} is any vector in V , then

$$\mathbf{v} = \langle \mathbf{v}, \mathbf{u}_1 \rangle \mathbf{u}_1 + \langle \mathbf{v}, \mathbf{u}_2 \rangle \mathbf{u}_2 + \cdots + \langle \mathbf{v}, \mathbf{u}_n \rangle \mathbf{u}_n$$

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As we have seen before, if $\mathbf{v} = c_1 \mathbf{u}_1 + \cdots + c_n \mathbf{u}_n$ then

$$\langle \mathbf{v}, \mathbf{u}_j \rangle = c_1 \langle \mathbf{u}_1, \mathbf{u}_j \rangle + \cdots + c_n \langle \mathbf{u}_n, \mathbf{u}_j \rangle = c_j$$