# Similar Matrices 

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## Theorem

Let $S$ be an invertible $n \times n$ matrix. Suppose $A$ and $B$ are two $n \times n$ matrices. Then $S^{-1} A B S=\left(S^{-1} A S\right)\left(S^{-1} B S\right)$. In particular, if $S$ is a transition matrix from a basis $\mathcal{B}$ of $\mathbb{R}^{n}$ to another basis $\mathcal{E}$, then the matrix representing $A B$ with respect to $\mathcal{B}$ is the product of the representing matrices for $A$ and $B$

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Example: Let $A=\left(\begin{array}{rrr}1 & 2 & 4 \\ 3 & -1 & -2 \\ 0 & 2 & 1\end{array}\right)$

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Example: Let $A=\left(\begin{array}{rrr}1 & 2 & 4 \\ 3 & -1 & -2 \\ 0 & 2 & 1\end{array}\right)$
If $L(\mathbf{x})=A \mathbf{x}$, find the representing matrix for $A$ relative to the basis

$$
\mathcal{B}=\left[\left(\begin{array}{l}
1 \\
0 \\
0
\end{array}\right),\left(\begin{array}{l}
1 \\
1 \\
0
\end{array}\right),\left(\begin{array}{l}
1 \\
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\end{array}\right)\right]
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If we find the transition matrix $S$ from $\mathcal{B}$ to $\mathcal{E}$ (the standard basis) we need to find $S^{-1} A S$.

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$$
\left(\begin{array}{lll|lll}
1 & 1 & 1 & 1 & 0 & 0 \\
0 & 1 & 1 & 0 & 1 & 0 \\
0 & 0 & 1 & 0 & 0 & 1
\end{array}\right) \xrightarrow{3 \mathrm{EROs}}\left(\begin{array}{lll|lrr}
1 & 0 & 0 & 1 & -1 & 0 \\
0 & 1 & 0 & 0 & 1 & -1 \\
0 & 0 & 1 & 0 & 0 & 1
\end{array}\right)
$$

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0 & 1 & 0 & 0 & 1 & -1 \\
0 & 0 & 1 & 0 & 0 & 1
\end{array}\right)
$$

Therefore, The required representing matrix for $L$ relative to $\mathcal{B}$ is

$$
S^{-1} A S=\left(\begin{array}{r}
-217 \\
30-3 \\
022
\end{array}\right)
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$$
\left(\begin{array}{lll|lll}
1 & 1 & 1 & 1 & 0 & 0 \\
0 & 1 & 1 & 0 & 1 & 0 \\
0 & 0 & 1 & 0 & 0 & 1
\end{array}\right) \xrightarrow{3 \mathrm{EROs}}\left(\begin{array}{lll|lrr}
1 & 0 & 0 & 1 & -1 & 0 \\
0 & 1 & 0 & 0 & 1 & -1 \\
0 & 0 & 1 & 0 & 0 & 1
\end{array}\right)
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S^{-1} A S=\left(\begin{array}{r}
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If we do the same for the transformation $T \mathbf{x}=B \mathbf{x}$ where
$B=\left(\begin{array}{rrr}1 & -1 & 0 \\ 2 & -2 & 1 \\ 0 & 0 & 1\end{array}\right)$
we get a representing matrix for $T$ relative to $\mathcal{B}$ :

$$
S^{-1} B S=\left(\begin{array}{rrr}
-1 & 0 & -1 \\
2 & 0 & 0 \\
0 & 0 & 1
\end{array}\right)
$$

Without computing $T(L(\mathbf{x}))=B A \mathbf{x}$, we can get the represention matrix for $T(L \mathbf{x})$ relative to $\mathcal{B}$ by multiplying these two representing matrices:

$$
\left(\begin{array}{rrr}
-1 & 0 & -1 \\
2 & 0 & 0 \\
0 & 0 & 1
\end{array}\right)\left(\begin{array}{rrr}
-2 & 1 & 7 \\
3 & 0 & -3 \\
0 & 2 & 2
\end{array}\right)=\left(\begin{array}{rrr}
2 & -3 & -9 \\
-4 & 2 & 14 \\
0 & 2 & 2
\end{array}\right)
$$

