# Row and Column Spaces 

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2. The column space of $A$ is the span of the columns of $A$. This is a subspace of $\mathbb{R}^{n}$ and consists of column vectors. (Later we will denote this by $\mathcal{R}(A)$, but it would be confusing to do that now.)
3. The row space of $A$ is the span of the rows of $A$. It is a subspace of $\mathbb{R}^{k}$ (interpreted as all $1 \times k$ row matrices). We don't have any special notation for this.

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This gives us the system

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\left.x_{1} \begin{array}{r}
+2 x_{3}-4 x_{4}=0 \\
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\end{array}\right\} \text { or }\left\{\begin{array}{l}
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Setting $x_{3}=\alpha$ and $x_{4}=\beta$ we get

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\mathcal{N}(A)=\left\{\left.\left(\begin{array}{c}
-2 \alpha+4 \beta \\
\alpha-2 \beta \\
\alpha \\
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\end{array}\right) \right\rvert\, \alpha \in \mathbb{R}\right\}=\operatorname{Span}\left(\left(\begin{array}{r}
-2 \\
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Notice that we get one element of the basis for each separate parameter. Thus, the dimension of $\mathcal{N}(A)$ (the size of a basis) is the number of free variables. That is the same as the number of columns without a leading 1 in the echelon form.

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\left(\begin{array}{rrrr}
0 & 2 & -2 & 4 \\
1 & 3 & -1 & 2 \\
-1 & -1 & -1 & 2
\end{array}\right) \xrightarrow{6 \mathrm{ERO}}\left(\begin{array}{rrrr}
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Notice that the dimension of the column space is the same as the number of columns with leading ones.

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The other is a bit easier and makes use of the fact that EROs do not change the row space: Every ERO does one of the following:

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1. Exchange 2 rows. The new matrix has the same rows so their span is the same.
2. Multiply a row times a nonzero number $\alpha$. One row, say $R_{1}$, is now $R_{1}^{\prime}=\alpha R_{1}$. But any linear combination that includes $R_{1}^{\prime}: c_{1} R_{1}^{\prime}+\cdots$, could be rewritten as $\left(\alpha c_{1}\right) R_{1}+\cdots$.

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3. Add a multiple of one row to another row. Suppose the new row is $R_{2}^{\prime}=R_{2}+\alpha R_{1}$. Then a linear combination that includes the new row: $c_{1} R_{1}+c_{2} R_{2}^{\prime}+\cdots$, can be written with the old row: $\left(c_{1}+\alpha c_{2}\right) R_{1}+c_{2} R_{2}+\cdots$.

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That means that if we reduce the matrix to echelon form the echelon form has the same row space.

For our example matrix, the matrix $A$ and its reduced echelon form $B$ are:

$$
A=\left(\begin{array}{rrrr}
0 & 2 & -2 & 4 \\
1 & 3 & -1 & 2 \\
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\end{array}\right) \quad \text { and } B=\left(\begin{array}{rrrr}
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$$
c_{1} R_{1}+c_{2} R_{2}=\left(\begin{array}{cccc}
c_{1} & c_{2} & 2 c_{1}-c_{2} & -4 c_{1}+2 c_{2}
\end{array}\right)
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This can only equal $\left(\begin{array}{cccc}0 & 0 & 0 & 0\end{array}\right)$ if $c_{1}=0$ and $c_{2}=0$.

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\left(\begin{array}{llll}
1 & 0 & 2 & -4
\end{array}\right),\left(\begin{array}{llll}
0 & 1 & -1 & 2
\end{array}\right)
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Let's summarize what these calculations gave us. Let $A$ be a matrix and let $B$ be its echelon form.

1. To find a basis for the null space of $A$, solve the system $A \mathbf{x}=\mathbf{0}$ by examining the echelon form (augmented) $(B \mid \mathbf{0})$.

One disadvantage of this method is that this set, while it is a basis of, the row space, it does not consist of any of the original rows. That may or may not be a problem. If it is, one can always find a basis for the column space of $A^{T}$ and transpose those vectors. If we did that in this example, we'd end up with first two rows of $A$.
We could also find a basis for the column space of $A$ by getting a basis for the row space of $A^{T}$ and turning them back into columns.
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Let $A$ be an $n \times k$ matrix. The rank of $A$ is the dimension of the column space of $A$. The nullity of $A$ is the dimension of the null space of $A$.

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The fourth is true because every column contains a leading 1 or does not.

