Vectors

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We will use the notation $\mathbb R$ to represent the set of all scalars (real numbers).

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There is a third way.



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- There are well-define ways to convert from one to to another.
- They all satisfy a common set of properties.

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A4. For all x in V, there is an element -x that satisfies -x + x = 0.

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A8. $1\mathbf{x} = \mathbf{x}$ (all \mathbf{x} in V)

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C2 If $a = -b$ and $c = -d$ is $(a + c, b + d)$ in V?

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Hidden in the definitions is the means to solve problems like $\mathbf{x} + \mathbf{a} = \mathbf{b}$ (obtaining $\mathbf{x} = \mathbf{b} - \mathbf{a}$) and like $\alpha \mathbf{x} = \mathbf{b}$ ($\mathbf{x} = \frac{1}{\alpha}\mathbf{b}$, provided $\alpha \neq 0$).

There are two ways new vector spaces can arise: a potential candidate occurs and/or is created, and someone verifies the 10 requirements. Or, one is created from a known vector space by applying some process or imposing some conditions.

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The first has already been done for the following cases:

- $\mathbb{R}^{n \times k}$ for all positive integers n and k (this includes \mathbb{R}^n)
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The verification of A1–A8 for $\mathbb{R}^{n \times k}$ is essentially the properties contained in section 1.4 (Matrix algebra). The zero element (called **0** here) is the matrix of 0s that I called \mathcal{O} back then. The negative of a matrix A is the matrix -A in which every entry of A has been negated: $-(a_{ij}) = (-a_{ij})$. Conditions C1 and C2 are part of the definition of scalar multiplication and addition for matrices. For functions f and g on a set S we define f + g to be that function which has values f(x) + g(x) for every x in S.

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$$\alpha \mathbf{0} = \alpha \mathbf{0} + \alpha \mathbf{0} - \alpha \mathbf{0} = \alpha (\mathbf{0} + \mathbf{0}) - \alpha \mathbf{0} = \alpha \mathbf{0} - \alpha \mathbf{0} = \mathbf{0}$$